

On the symplectic nonsqueezing

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In a recent paper accepted by *Acta Mathematica*, McDuff and Siegel (McDuff and Siegel 2024) computed, for every stabilized four-dimensional ellipsoid, the smallest stabilized four-ball into which it can be symplectically embedded. Their result settles a major open problem in symplectic geometry.

Symplectic geometry is an even-dimensional geometry that measures the signed areas of two-dimensional objects. To begin with a simple case, let $S \subset \mathbb{R}^2$ be an open region in the plane, together with a choice of orientation, that is, a direction in which to traverse its boundary ∂S . The *symplectic area* $\omega(S)$ is the real number whose absolute value $|\omega(S)|$ is the usual Euclidean area of S , and whose sign is positive if the orientation is anticlockwise and negative if it is clockwise.

More generally, if S is an oriented two-dimensional surface in \mathbb{R}^{2n} , we define its symplectic area by projecting it to each coordinate plane (x_{2i-1}, x_{2i}) and summing the signed areas:

$$\omega(S) = \sum_{i=1}^n \omega(S_i),$$

where S_i denotes the projection of S to the (x_{2i-1}, x_{2i}) -plane. If $U, V \subset \mathbb{R}^{2n}$, we say that U *embeds symplectically* into V , and write

$$U \xrightarrow{s} V,$$

if there is a smooth embedding $\phi : U \rightarrow \mathbb{R}^{2n}$ such that (i) $\phi(U) \subset V$, (ii) ϕ is a diffeomorphism from U onto its image, and (iii) ϕ preserves symplectic area:

$$\omega(S) = \omega(\phi(S))$$

for every oriented surface $S \subset U$.

Questions about symplectic embeddings lie at the heart of symplectic geometry. For instance, Gromov's celebrated non-squeezing theorem says that the Euclidean ball

$$B^{2n}(r) := \left\{ x \in \mathbb{R}^{2n} : \sum_{i=1}^{2n} x_i^2 \leq r^2 \right\}$$

of radius $r > 0$ embeds symplectically into the cylinder

$$Z^{2n}(R) := B^2(R) \times \mathbb{R}^{2(n-1)} = \{x \in \mathbb{R}^{2n} : x_1^2 + x_2^2 \leq R^2\} \quad (1)$$

if and only if $r \leq R$. Thus, although the cylinder is unbounded in all but two directions, the two-dimensional radius of its base still imposes a rigid obstruction to symplectic embeddings.

One consequence is that if the symplectic *polydisk*

$$P(R_1, \dots, R_n) := B^2(R_1) \times \dots \times B^2(R_n),$$

with positive radii R_1, \dots, R_n , embeds symplectically into another polydisk

$$P(R'_1, \dots, R'_n),$$

then

$$\min_i R_i \leq \min_i R'_i.$$

Conservation of volume gives another necessary condition:

$$\prod_{i=1}^n R_i \leq \prod_{i=1}^n R'_i.$$

In 2008, Guth (Guth 2008) proved that, up to a constant factor depending only on the dimension, these obvious necessary conditions are also sufficient.

Theorem 1 *For every $n \geq 1$, there is a constant $C_n > 0$ such that if*

$$C_n \min_i R_i \leq \min_i R'_i \quad \text{and} \quad C_n \prod_{i=1}^n R_i \leq \prod_{i=1}^n R'_i,$$

then

$$P(R_1, \dots, R_n) \xrightarrow{s} P(R'_1, \dots, R'_n).$$

Theorem 1 has many striking consequences. For example, it implies that there is a constant R such that

$$B^2(1) \times B^{2(n-1)}(S) \xrightarrow{s} B^4(R) \times \mathbb{R}^{2(n-2)}$$

for every $S > 0$. In 2014, Hind and Kerman (Hind and Kerman 2014) proved that the infimum of all such constants R is exactly $\sqrt{3}$.

Theorem 2 *Fix $n \geq 3$. For every $R > \sqrt{3}$,*

$$B^2(1) \times B^{2(n-1)}(S) \xrightarrow{s} B^4(R) \times \mathbb{R}^{2(n-2)}$$

for all $S > 0$. Conversely, for every $0 < R < \sqrt{3}$, there is a constant $S_0 = S_0(R, n)$ such that, for all $S > S_0$, there is no symplectic embedding

$$B^2(1) \times B^{2(n-1)}(S) \xrightarrow{s} B^4(R) \times \mathbb{R}^{2(n-2)}.$$

Theorems 1 and 2 concern balls and products of balls, which are among the most tractable examples in symplectic geometry. Another natural class of domains is given by ellipsoids. For a real number $a \geq 1$, define the four-dimensional symplectic ellipsoid

$$E_a := \left\{ x \in \mathbb{R}^4 : x_1^2 + x_2^2 + \frac{x_3^2 + x_4^2}{a} \leq 1 \right\}.$$

Let $c_{\text{ell}}(a)$ denote the infimum of all $\mu > 0$ such that

$$E_a \xrightarrow{s} B^4(\sqrt{\mu}).$$

Equivalently, $c_{\text{ell}}(a)$ measures how much the radius of the target ball must be enlarged, in squared-radius units, in order to contain a symplectic image of E_a . Conservation of volume implies

$$c_{\text{ell}}(a) \geq \sqrt{a}$$

for all $a \geq 1$. It is also not hard to see that $c_{\text{ell}}(a)$ is nondecreasing and continuous. The exact computation of this function was a long-standing problem, solved by McDuff and Schlenk (McDuff and Schlenk 2012) in 2012.

Let F_n , $n \geq 0$, be the Fibonacci numbers:

$$F_0 = 0, \quad F_1 = 1, \quad F_{n+2} = F_{n+1} + F_n.$$

Set

$$\alpha_0 := 1, \quad \beta_0 := 2,$$

and, for $k \geq 1$, define

$$\alpha_k := \frac{F_{2k+1}^2}{F_{2k-1}^2}, \quad \beta_k := \frac{F_{2k+3}}{F_{2k-1}}.$$

Then

$$1 = \alpha_0 < \beta_0 < \alpha_1 < \beta_1 < \alpha_2 < \cdots,$$

and these numbers converge to

$$\tau^4, \quad \tau = \frac{1 + \sqrt{5}}{2}.$$

The graph of $c_{\text{ell}}(a)$ contains an infinite staircase on the interval $[1, \tau^4]$, now known as the Fibonacci staircase.

Theorem 3 For every real number $a \geq 1$, the function $c_{\text{ell}}(a)$ has the following form.

(i) For every $k \geq 0$,

$$c_{\text{ell}}(a) = \frac{a}{\sqrt{\alpha_k}} \quad \text{for } a \in [\alpha_k, \beta_k],$$

and

$$c_{\text{ell}}(a) = \sqrt{\alpha_{k+1}} \quad \text{for } a \in [\beta_k, \alpha_{k+1}].$$

(ii) For $\tau^4 \leq a \leq 7$,

$$c_{\text{ell}}(a) = \frac{a+1}{3}.$$

(iii) There are finitely many pairwise disjoint closed intervals

$$I_j \subset \left[7, 8\frac{1}{36}\right]$$

such that

$$c_{\text{ell}}(a) = \sqrt{a}$$

for all $a > 7$ with $a \notin I_j$ for every j . Moreover, on each interval I_j , the function $c_{\text{ell}}(a)$ is piecewise linear and has exactly one nonsmooth point in the interior of I_j .

(iv) For $a \geq 8\frac{1}{36}$,

$$c_{\text{ell}}(a) = \sqrt{a}.$$

For a positive integer n , the product

$$U \times \mathbb{R}^{2n}$$

is obtained from a four-dimensional region $U \subset \mathbb{R}^4$ by adjoining $2n$ extra unbounded real coordinates. This operation is called *stabilization*. The stabilized analogue of $c_{\text{ell}}(a)$ is

$$c_{B^4 \times \mathbb{R}^{2n}}(a) := \inf \left\{ \mu > 0 : E_a \times \mathbb{R}^{2n} \xrightarrow{s} B^4(\sqrt{\mu}) \times \mathbb{R}^{2n} \right\}.$$

Thus $c_{B^4 \times \mathbb{R}^{2n}}(a)$ measures how much the round four-ball factor must be enlarged before the stabilized ellipsoid embeds symplectically into it. Upper and lower bounds for this quantity, for various values of a , have been studied by many authors.

In their recent paper, McDuff and Siegel (McDuff and Siegel 2024) computed

$$c_{B^4 \times \mathbb{R}^{2n}}(a)$$

exactly for every $a \geq 1$. Their result gives a stabilized counterpart of Theorem 3.

Theorem 4 For every positive integer n and every real number $a \geq 1$,

$$c_{B^4 \times \mathbb{R}^{2n}}(a) = \begin{cases} \frac{a}{\sqrt{\alpha_k}}, & \text{if } a \in [\alpha_k, \beta_k] \text{ for some } k \geq 0, \\ \sqrt{\alpha_{k+1}}, & \text{if } a \in [\beta_k, \alpha_{k+1}] \text{ for some } k \geq 0, \\ \frac{3a}{a+1}, & \text{if } a \in [\tau^4, \infty). \end{cases}$$

In particular,

$$c_{B^4 \times \mathbb{R}^{2n}}(a) = c_{\text{ell}}(a)$$

for

$$1 \leq a \leq \tau^4.$$

That is, stabilization does not change the embedding function along the Fibonacci staircase. Beyond the staircase, however, the stabilized problem behaves very differently from the four-dimensional one. Instead of eventually becoming governed by the volume constraint

$$c_{\text{ell}}(a) = \sqrt{a},$$

the stabilized function is

$$c_{B^4 \times \mathbb{R}^{2n}}(a) = \frac{3a}{a+1}$$

for all

$$a \geq \tau^4.$$

The previously known upper bound is therefore sharp. The new contribution of McDuff and Siegel (McDuff and Siegel 2024) is the matching lower bound for every $a \geq \tau^4$.

References

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